## Decomposition Polyhedra of Piecewise Linear Functions

**DISCOGA Seminar** 

November 8, 2025 Moritz Grillo

Joint work with





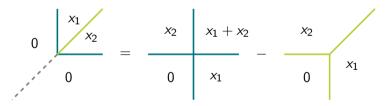
Marie-Charlotte Brandenburg (RUB) and Christoph Hertrich (UTN)

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- ▶ CPWL functions are the functions representable by ReLU neural networks
- Nonconvexity complicates optimization and neural network representations.
- Every CPWL function f can be written as difference of two convex CPWL functions g h [Melzer, 1986; Kripfganz and Schulze, 1987].



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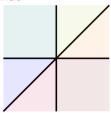
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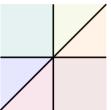
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- 1. Crash course on CPWL functions
- 2. Decomposition Polyhedra
- 3. Submodular functions

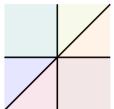
$$ightharpoonup$$
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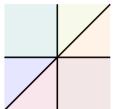
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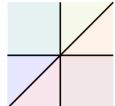


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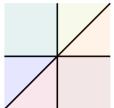
#### A **polyhedral complex** $\mathcal{P}$ is a collection of polyhedra such that

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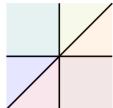
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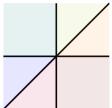
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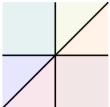
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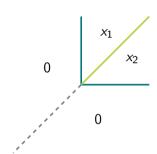
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- $\blacktriangleright$  If all polyhedra are cones, then we all  ${\cal P}$  a polyhedral fan.

#### Definition

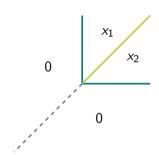
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We call f and  $\mathcal{P}$  **compatible** with each other.



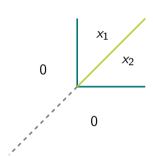
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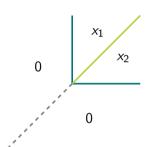
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### Number of pieces

- $ightharpoonup f|_P$  is a linear component of f.
- ▶ The **number of pieces** q of f is the smallest possible number of regions  $|\mathcal{P}^d|$  of a compatible polyhedral complex  $\mathcal{P}$ .



▶ If *f* is a **convex** CPWL function, then

$$f(x) = \max_{i \in [k]} \{ \langle a_i, x \rangle + b_i \}$$

for affine functions  $x \mapsto \langle a_i, x \rangle + b_i$ .

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▶ Then  $\mathcal{P}_f^d = \{P_i \mid i \in [k]\}$  with

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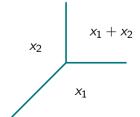
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- ► Number of pieces = number of linear components
- ightharpoonup Example:  $\max\{x_1, x_2, x_1 + x_2\}$



## **Existing Decompositions**

Hyperplane extension

Kripfganz and Schulze '87 Zalgaller '00 Schlüter and Darup '21 Local maxima decomposition

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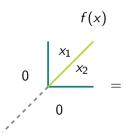
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### Local maxima decomposition

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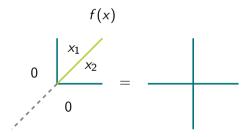
- Both methods already discovered by Kripfganz and Schulze in 1987
- Local maxima decomposition is refinement of the hyperplane extension in the worst case

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- 2. For each  $P, Q \in \mathcal{P}^d$  with and f convex at  $P \cap Q \in \mathcal{P}^{d-1}$  define

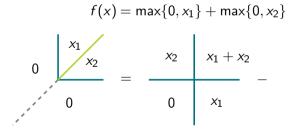
$$g_{P,Q}(x) = \max\{\langle a_P, x \rangle + b_P, \langle a_Q, x \rangle + b_Q\}$$



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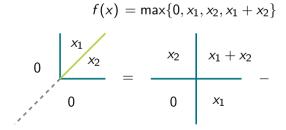
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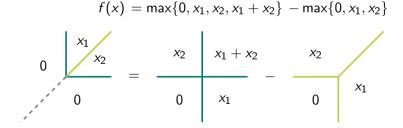
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$$f(x) = \max\{0, x_1, x_2, x_1 + x_2\} - \max\{0, x_1, x_2\}$$

$$0$$

$$0$$

$$x_1$$

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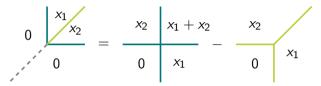
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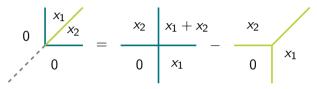
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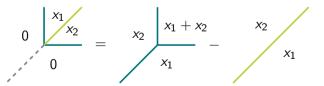
▶ But: If f has q pieces, g and h can have  $O(q^d)$  many pieces

Is this construction optimal?



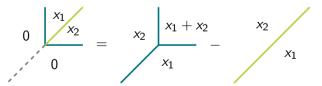
Is this construction optimal? No!





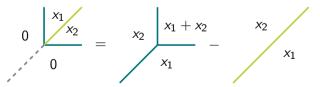
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Is this construction optimal? Yes!



Let the CPWL function f be compatible with  $\mathcal{P}$ 

▶ For  $P \in \mathcal{P}^d$ , let  $a_P \in \mathbb{R}^d$ ,  $b_P \in \mathbb{R}$  such that  $f(x) = \langle a_P, x \rangle + b_P$  for  $x \in P$ 

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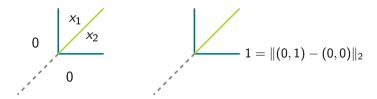
▶ Define 
$$w_f(\sigma) = \begin{cases} \|a_P - a_Q\|_2 & \text{f locally convex around } \sigma \\ -\|a_P - a_Q\|_2 & \text{f locally concave around } \sigma \end{cases}$$

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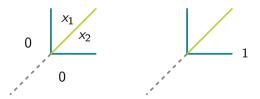




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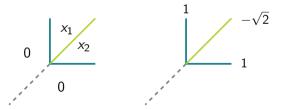
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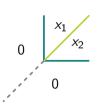
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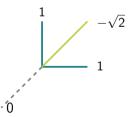


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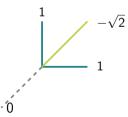
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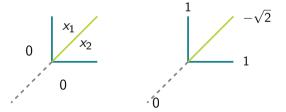
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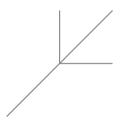
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- ▶ For  $\sigma \in \mathcal{P}^{d-1}$ , let P and Q be the unique polyhedra such that  $P \cap Q = \sigma$
- ▶ Define  $w_f(\sigma) = \begin{cases} \|a_P a_Q\|_2 & \text{f locally convex around } \sigma \\ -\|a_P a_Q\|_2 & \text{f locally concave around } \sigma \end{cases}$

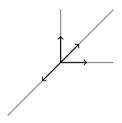


▶ Then  $(P, w_f)$  is a balanced complex.

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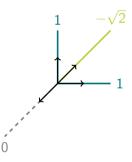


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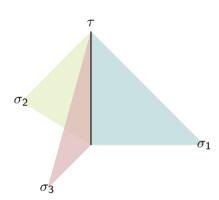
$$\begin{array}{c} 1 & -\sqrt{2} \\ \hline \end{array}$$

 $\sum w(\sigma)r_{\sigma}=0$ 

$$\sum_{\sigma \in \Gamma} w(\sigma) r_{\sigma} = 1 \cdot (1,0) - \sqrt{2} \cdot (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}) + 1 \cdot (0,1) = (0,0)$$

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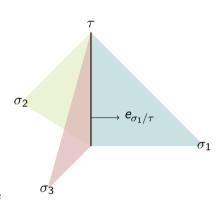
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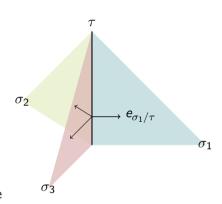
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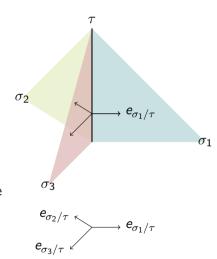
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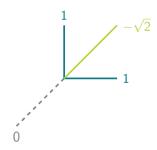
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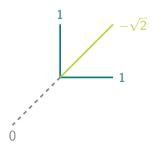
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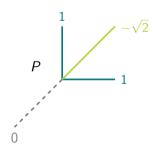


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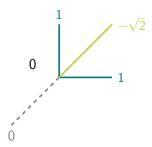


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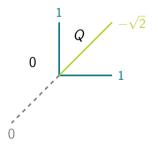
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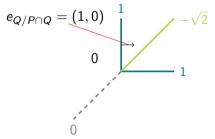
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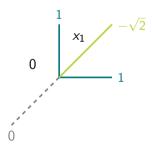
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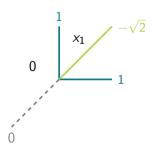
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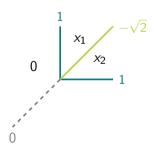
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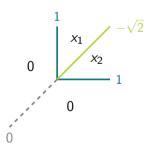
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- ▶ Iterate
- Balancing condition ensures that prodecure is well-defined



### **Newton Polytopes**

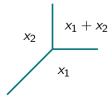
### Bijection between convex CPWL functions and polytopes

▶ A **positively homogeneous** convex CPWL function is a function f such that f(0) = 0, and  $\mathcal{P}_f$  is a polyhedral fan.

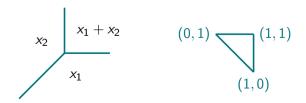
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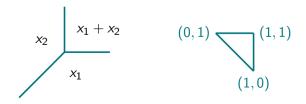
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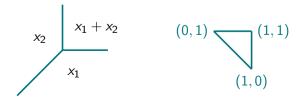
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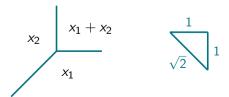
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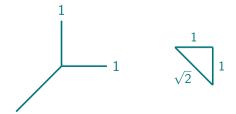
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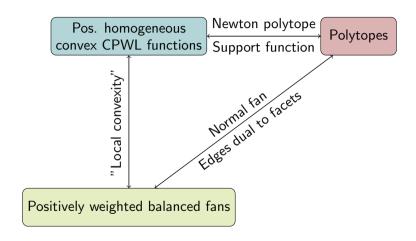
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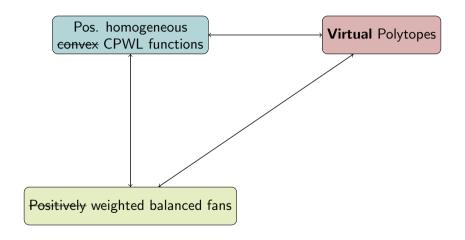
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# Summary



# Allowing Subtraction

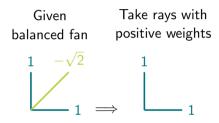


Theorem (Tran and Wang, 2024)

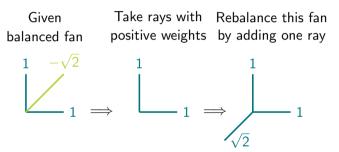
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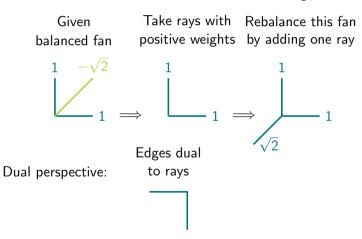
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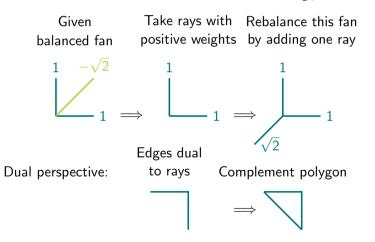
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## Conjecture for higher dimension

► For every  $\tau \in \mathcal{P}^{d-2}$ , let  $\sigma_1, \ldots, \sigma_k \in \mathcal{P}^{d-1}$  be the facets containing  $\tau$  with  $w_f(\sigma_i) > 0$ 

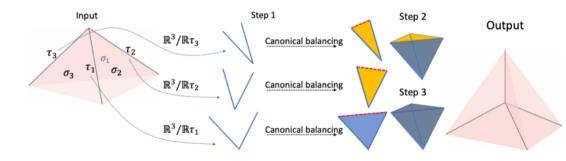


Figure: Figure from [Tran and Wang]

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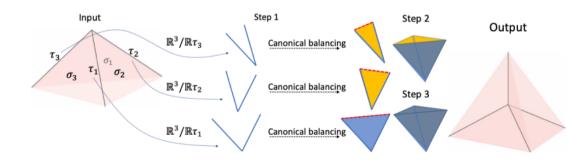


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- Construct the polygon  $P_{\tau}$  dual to  $\sigma_1/\tau, \ldots, \sigma_k/\tau$  in the 2-dimensional space orthogonal to span $(\tau)$
- ▶ Glue the polygons  $P_{\tau}$  together along edges corresponding to the same facets  $\sigma$  and take the convex hull

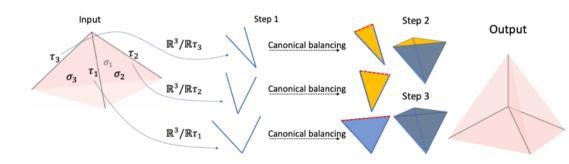
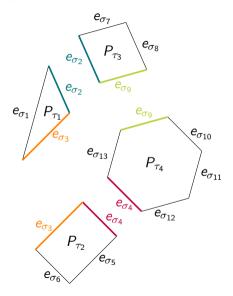


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# Counterexample to Conjecture



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- Describe the space of all decompositions. But this space lies in a infinite-dimensional vector space....
- ➤ To make the problem more tractable: Fix the possible breakpoints of the decompositions

#### Some observations

 $ightharpoonup \mathcal{V}_{\mathcal{P}} \coloneqq \mathsf{set} \ \mathsf{of} \ \mathsf{all} \ \mathsf{CPWL} \ \mathsf{function} \ \mathsf{compatible} \ \mathsf{with} \ \mathcal{P} \ \mathsf{is} \ \mathsf{a} \ \mathsf{vector} \ \mathsf{space}.$ 

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- $\triangleright$   $\overline{\mathcal{V}_{\mathcal{D}}}$  is finite dimensional and the set of all convex functions

$$\overline{\mathcal{V}_{\mathcal{P}}^{+}} \cong \mathcal{W}_{\mathcal{P}}^{+} := \bigcap_{\sigma \in \mathcal{P}^{d-1}} \{ w \in \mathcal{W}_{\mathcal{P}} \mid w(\sigma) \geq 0 \}$$

is a polyhedral cone.

# Decomposition Polyhedra

### **Definition**

For f compatible with  $\mathcal{P}$ , we define the **decomposition polyhedra** as

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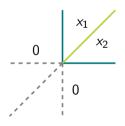


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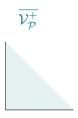
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  - $\triangleright$  where g' has at most as many pieces as g, h' has at most as many pieces as h,

- A decomposition  $(g, h) \in \mathcal{D}_{\mathcal{P}}(f)$  is called **reduced**, if there is no non-linear convex function  $\phi \in \overline{\mathcal{V}_{\mathcal{P}}^+} \setminus \{0\}$  such that  $g \phi$  and  $h \phi$  are both convex.
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  - and one of the two has strictly fewer pieces.

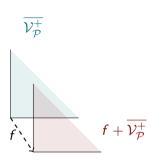
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 $\triangleright \mathcal{D}_{\mathcal{P}}(f)$  is a polyhedron that arises as the intersection of two shifted cones.



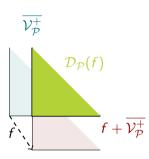
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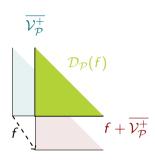
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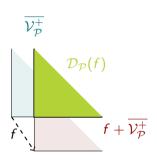
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## Structure of the Decomposition Polyhedra

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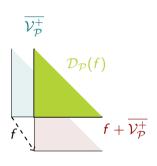
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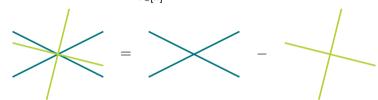
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- ▶ **Finite procedure** to find minimal decomposition among decompositions in  $\mathcal{D}_{\mathcal{P}}(f)$ .

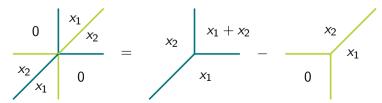


### Cases with a unique vertex

▶ Hyperplane functions  $f(x) = \sum_{i \in [k]} \lambda_i \cdot \max\{\langle x, a_i \rangle, \langle x, b_i \rangle\}$ 

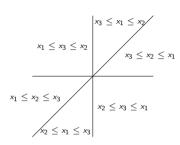


▶ The function  $f: \mathbb{R}^n \to \mathbb{R}$  that returns the k-th largest entry of an input vector  $x \in \mathbb{R}^n$ .



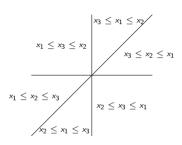
#### Braid arrangement

▶ The **braid arrangement** in  $\mathbb{R}^d$  is the hyperplane arrangement consisting of the  $\binom{d}{2}$  hyperplanes  $x_i = x_j$ , with  $1 \le i < j \le d$ .



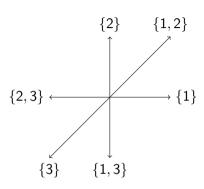
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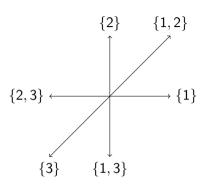
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#### Lemma

The mapping  $\Phi$  that maps  $f \in \mathcal{V}_{\mathcal{B}}$  to the set function  $F(S) = f(\mathbb{1}_S)$  is a vector space isomorphism, where  $\mathbb{1}_S = \sum_{i \in S} e_i$ .

A set function  $F: 2^{[d]} \to \mathbb{R}$  is called **submodular** if

$$F(A) + F(B) \ge F(A \cup B) + F(A \cap B)$$

for all  $A, B \subseteq [d]$  and  $F(\emptyset) = 0$ .

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The **base polytope** B(F) is defined by the inequalities  $\sum_{i \in S} x_i \leq F(S)$  for all  $S \subset [d]$  and  $\sum_{i \in [d]} x_i = F([d])$ .

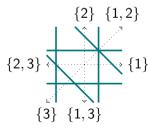
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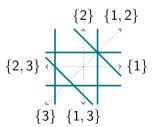
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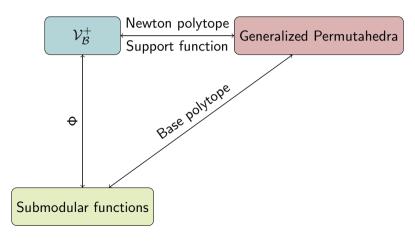
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A function f is convex if and only if  $\Phi(f)$  is submodular.

How to decompose a set function into a difference of submodular functions such that their base polytopes have as few vertices as possible?



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#### The decomposition polyhedra can be very complex

We do not even know the number of rays of the submodular cone for d > 5...

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# Thank you for your attention!